

# Lecture Notes 7

## Stationary Random Processes

---

- Strict-Sense and Wide-Sense Stationarity
- Autocorrelation Function of a Stationary Process
- Power Spectral Density
- Stationary Ergodic Random Processes

# Stationary Random Processes

---

- Stationarity refers to **time invariance** of some, or all, of the statistics of a random process, such as mean, autocorrelation,  $n$ -th-order distribution
- We define two types of stationarity: **strict sense** (SSS) and **wide sense** (WSS)
- A random process  $X(t)$  (or  $X_n$ ) is said to be SSS if **all** its finite order distributions are time invariant, i.e., the joint cdfs (pdfs, pmfs) of

$$X(t_1), X(t_2), \dots, X(t_k) \quad \text{and} \quad X(t_1 + \tau), X(t_2 + \tau), \dots, X(t_k + \tau)$$

are the same for all  $k$ , all  $t_1, t_2, \dots, t_k$ , and all time shifts  $\tau$

- So for a SSS process, the first-order distribution is independent of  $t$ , and the second-order distribution — the distribution of any two samples  $X(t_1)$  and  $X(t_2)$  — depends only on  $\tau = t_2 - t_1$

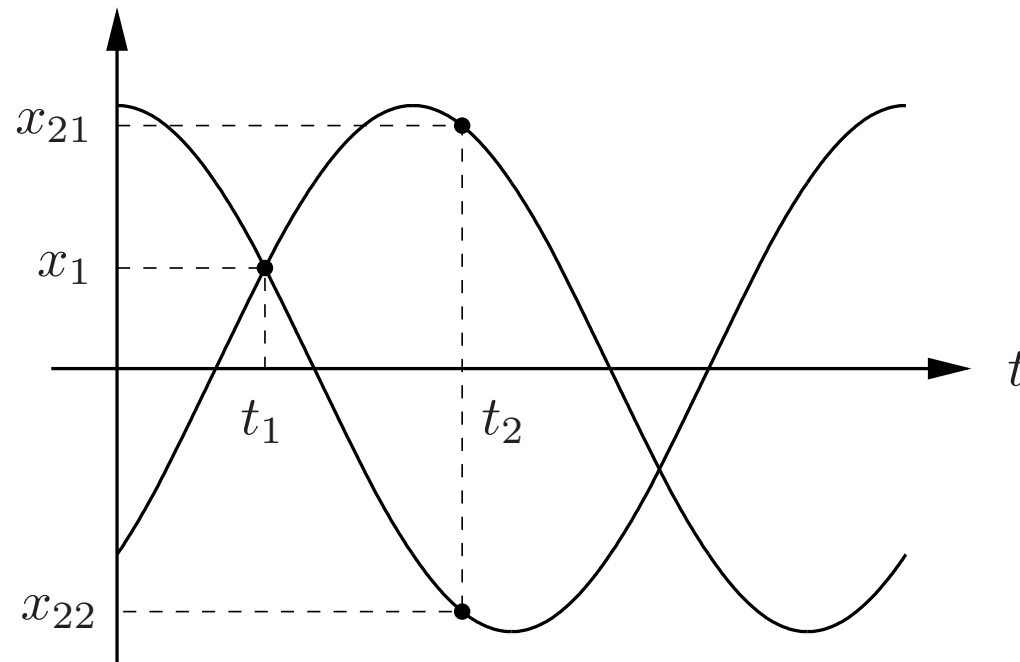
To see this, note that from the definition of stationarity, for any  $t$ , the joint distribution of  $X(t_1)$  and  $X(t_2)$  is the same as the joint distribution of  $X(t_1 + (t - t_1)) = X(t)$  and  $X(t_2 + (t - t_1)) = X(t + (t_2 - t_1))$

- Example: The random phase signal  $X(t) = \alpha \cos(\omega t + \Theta)$  where  $\Theta \in U[0, 2\pi]$  is SSS
  - We already know that the first order pdf is

$$f_{X(t)}(x) = \frac{1}{\pi\alpha\sqrt{1 - (x/\alpha)^2}}, \quad -\alpha < x < +\alpha$$

which is independent of  $t$ , and is therefore stationary

- To find the second order pdf, note that if we are given the value of  $X(t)$  at one point, say  $t_1$ , there are (at most) two possible sample functions:



The second order pdf can thus be written as

$$\begin{aligned} f_{X(t_1), X(t_2)}(x_1, x_2) &= f_{X(t_1)}(x_1) f_{X(t_2)|X(t_1)}(x_2|x_1) \\ &= f_{X(t_1)}(x_1) \left( \frac{1}{2} \delta(x_2 - x_{21}) + \frac{1}{2} \delta(x_2 - x_{22}) \right), \end{aligned}$$

which depends only on  $t_2 - t_1$ , and thus the second order pdf is stationary

- Now if we know that  $X(t_1) = x_1$  and  $X(t_2) = x_2$ , the sample path is totally determined (except when  $x_1 = x_2 = 0$ , where two paths may be possible), and thus all  $n$ -th order pdfs are stationary
- IID processes are SSS
- Random walk and Poisson processes are not SSS
- The Gauss-Markov process (as we defined it) is not SSS. However, if we set  $X_1$  to the steady state distribution of  $X_n$ , it becomes SSS (see homework exercise)

# Wide-Sense Stationary Random Processes

---

- A random process  $X(t)$  is said to be **wide-sense stationary** (WSS) if its mean and autocorrelation functions are time invariant, i.e.,
  - $E(X(t)) = \mu$ , independent of  $t$
  - $R_X(t_1, t_2)$  is a function only of the time difference  $t_2 - t_1$
  - $E[X(t)^2] < \infty$  (technical condition)
- Since  $R_X(t_1, t_2) = R_X(t_2, t_1)$ , for any wide sense stationary process  $X(t)$ ,  $R_X(t_1, t_2)$  is a function only of  $|t_2 - t_1|$
- Clearly SSS  $\Rightarrow$  WSS. The converse is not necessarily true

- Example: Let

$$X(t) = \begin{cases} + \sin t & \text{with probability } \frac{1}{4} \\ - \sin t & \text{with probability } \frac{1}{4} \\ + \cos t & \text{with probability } \frac{1}{4} \\ - \cos t & \text{with probability } \frac{1}{4} \end{cases}$$

- $E(X(t)) = 0$  and  $R_X(t_1, t_2) = \frac{1}{2} \cos(t_2 - t_1)$ , thus  $X(t)$  is WSS
- But  $X(0)$  and  $X(\frac{\pi}{4})$  do not have the same pmf (different ranges), so the first order pmf is not stationary, and the process is not SSS
- For Gaussian random processes,  $WSS \Rightarrow SSS$ , since the process is completely specified by its mean and autocorrelation functions
- Random walk is not WSS, since  $R_X(n_1, n_2) = \min\{n_1, n_2\}$  is not time invariant; similarly Poisson process is not WSS

# Autocorrelation Function of WSS Processes

---

• Let  $X(t)$  be a WSS process. Relabel  $R_X(t_1, t_2)$  as  $R_X(\tau)$  where  $\tau = t_1 - t_2$

1.  $R_X(\tau)$  is real and even, i.e.,  $R_X(\tau) = R_X(-\tau)$  for every  $\tau$

2.  $|R_X(\tau)| \leq R_X(0) = \mathbb{E}[X^2(t)]$ , the “average power” of  $X(t)$

This can be shown as follows. For every  $t$ ,

$$\begin{aligned}(R_X(\tau))^2 &= [\mathbb{E}(X(t)X(t + \tau))]^2 \\ &\leq \mathbb{E}[X^2(t)] \mathbb{E}[X^2(t + \tau)] \quad \text{by Schwarz inequality} \\ &= (R_X(0))^2 \quad \text{by stationarity}\end{aligned}$$

3. If  $R_X(T) = R_X(0)$  for some  $T \neq 0$ , then  $R_X(\tau)$  is periodic with period  $T$  and so is  $X(t)$  (with probability 1) !! That is,

$$R_X(\tau) = R_X(\tau + T), \quad X(\tau) = X(\tau + T) \text{ w.p.1 for every } \tau$$

- Example: The autocorrelation function for the periodic signal with random phase  $X(t) = \alpha \cos(\omega t + \Theta)$  is  $R_X(\tau) = \frac{\alpha^2}{2} \cos \omega \tau$  (also periodic)

- To prove property 3, we again use the Schwarz inequality: For every  $\tau$ ,

$$\begin{aligned} [R_X(\tau) - R_X(\tau + T)]^2 &= [\mathbf{E}(X(t)(X(t + \tau) - X(t + \tau + T)))]^2 \\ &\leq \mathbf{E}[X^2(t)] \mathbf{E}[(X(t + \tau) - X(t + \tau + T))^2] \\ &= R_X(0)(2R_X(0) - 2R_X(T)) \\ &= R_X(0)(2R_X(0) - 2R_X(0)) = 0 \end{aligned}$$

Thus  $R_X(\tau) = R_X(\tau + T)$  for all  $\tau$ , i.e.,  $R_X(\tau)$  is periodic with period  $T$

- The above properties of  $R_X(\tau)$  are necessary but not sufficient for a function to qualify as an autocorrelation function for a WSS process



- The necessary and sufficient conditions for a function to be an autocorrelation function for a WSS process is that it be **real**, **even**, and **nonnegative definite**

By nonnegative definite we mean that for any  $n$ , any  $t_1, t_2, \dots, t_n$  and any real vector  $\mathbf{a} = (a_1, \dots, a_n)$ ,

$$\sum_{i=1}^n \sum_{j=1}^n a_i a_j R(t_i - t_j) \geq 0$$

To see why this is necessary, recall that the correlation matrix for a random vector must be nonnegative definite, so if we take a set of  $n$  samples from the WSS random process, their correlation matrix must be nonnegative definite

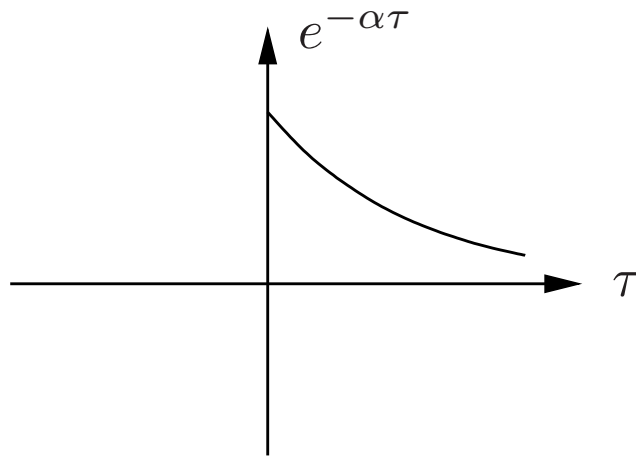
The condition is sufficient since such an  $R(\tau)$  can specify a zero mean stationary Gaussian random process

- The nonnegative definite condition may be difficult to verify directly. It turns out, however, to be equivalent to the condition that the Fourier transform of  $R_X(\tau)$ , which is called the **power spectral density**  $S_X(f)$ , is nonnegative for all frequencies  $f$

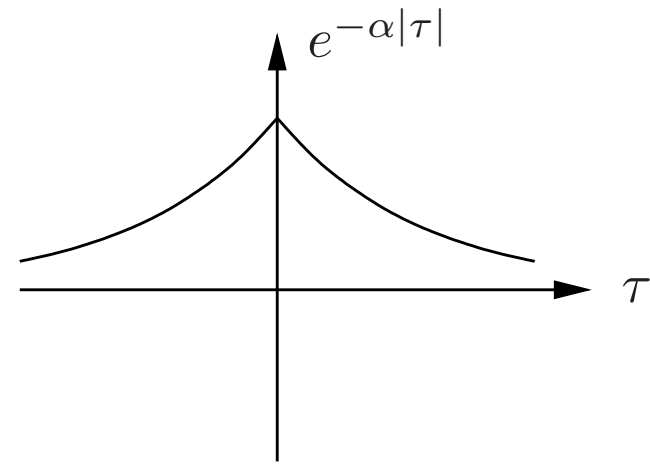
# Which Functions Can Be an $R_X(\tau)$ ?

---

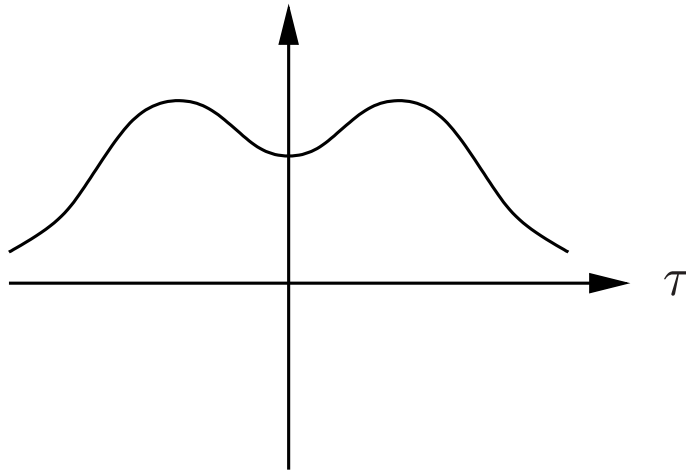
1.



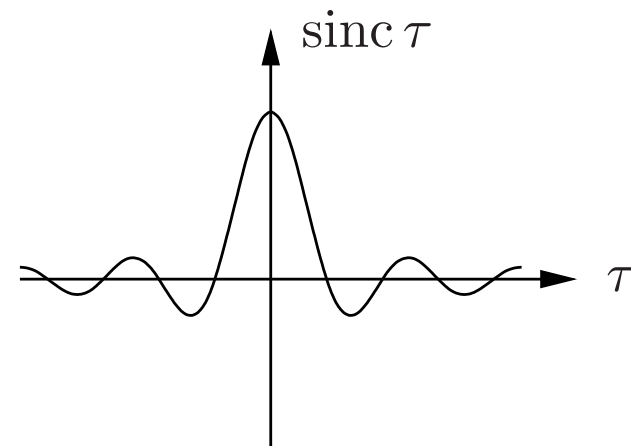
2.



3.



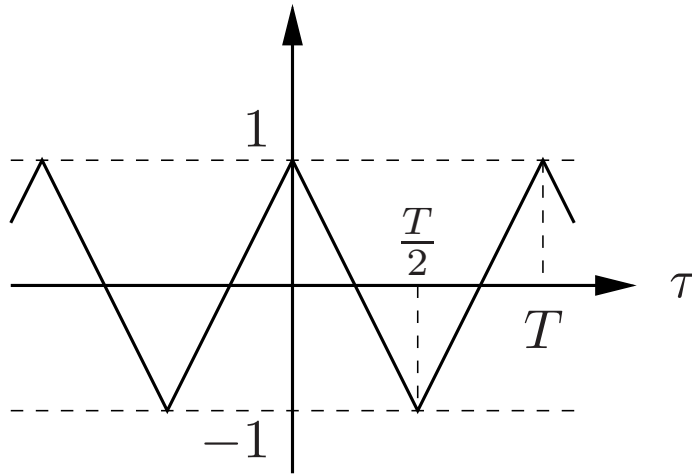
4.



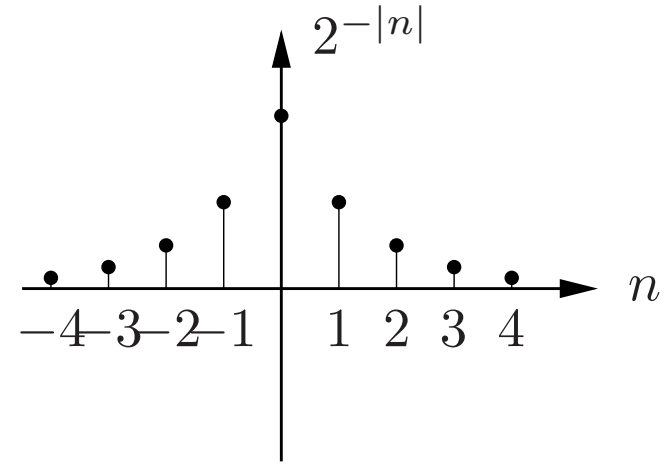
# Which Functions can be an $R_X(\tau)$ ?

---

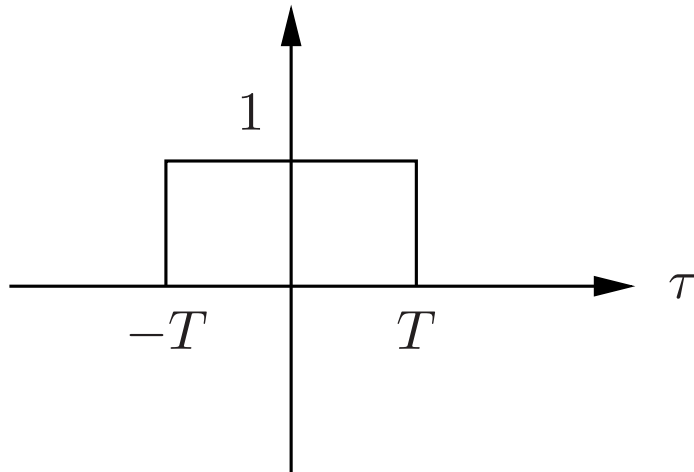
5.



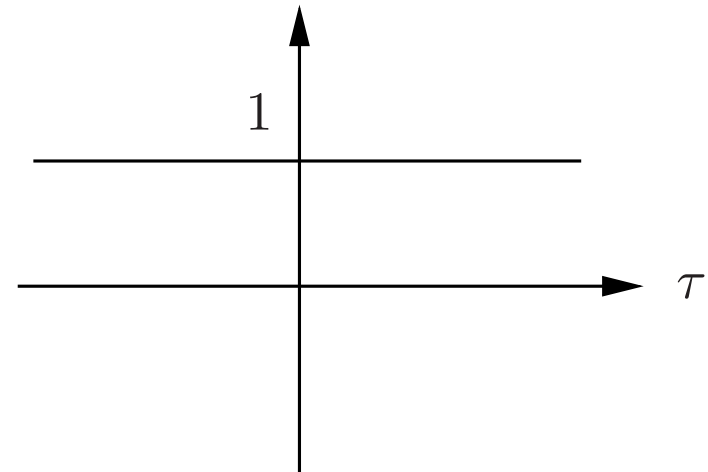
6.



7.

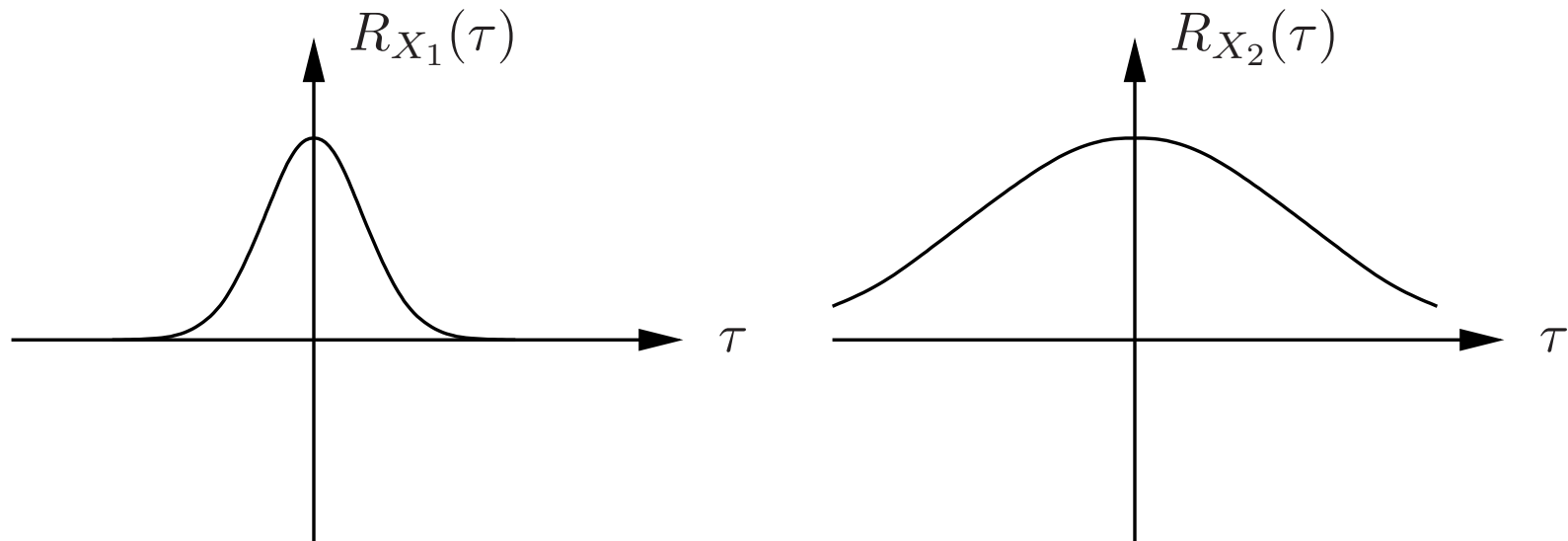


8.



# Interpretation of Autocorrelation Function

- Let  $X(t)$  be WSS with zero mean. If  $R_X(\tau)$  drops quickly with  $\tau$ , this means that samples become uncorrelated quickly as we increase  $\tau$ . Conversely, if  $R_X(\tau)$  drops slowly with  $\tau$ , samples are highly correlated



- So  $R_X(\tau)$  is a measure of the rate of change of  $X(t)$  with time  $t$ , i.e., **the frequency response** of  $X(t)$
- It turns out that this is not just an intuitive interpretation — the Fourier transform of  $R_X(\tau)$  (the power spectral density) is in fact the average power density of  $X(t)$  over frequency

# Power Spectral Density

---

- The **power spectral density** (psd) of a WSS random process  $X(t)$  is the Fourier transform of  $R_X(\tau)$ :

$$S_X(f) = \mathcal{F}(R_X(\tau)) = \int_{-\infty}^{\infty} R_X(\tau) e^{-i2\pi\tau f} d\tau$$

- For a discrete time process  $X_n$ , the power spectral density is the discrete-time Fourier transform (DTFT) of the sequence  $R_X(n)$ :

$$S_X(f) = \sum_{n=-\infty}^{\infty} R_X(n) e^{-i2\pi n f}, \quad |f| < \frac{1}{2}$$

- $R_X(\tau)$  (or  $R_X(n)$ ) can be recovered from  $S_X(f)$  by taking the inverse Fourier transform or inverse DTFT:

$$R_X(\tau) = \int_{-\infty}^{\infty} S_X(f) e^{i2\pi\tau f} df$$

$$R_X(n) = \int_{-\frac{1}{2}}^{\frac{1}{2}} S_X(f) e^{i2\pi n f} df$$

# Properties of the Power Spectral Density

---

1.  $S_X(f)$  is real and even, since the Fourier transform of the real and even function  $R_X(\tau)$  is real and even
2.  $\int_{-\infty}^{\infty} S_X(f) df = R_X(0) = E(X^2(t))$ , the average power of  $X(t)$ , i.e., the area under  $S_X$  is the average power
3.  $S_X(f)$  is **the average power density**, i.e., the average power of  $X(t)$  in the frequency band  $[f_1, f_2]$  is

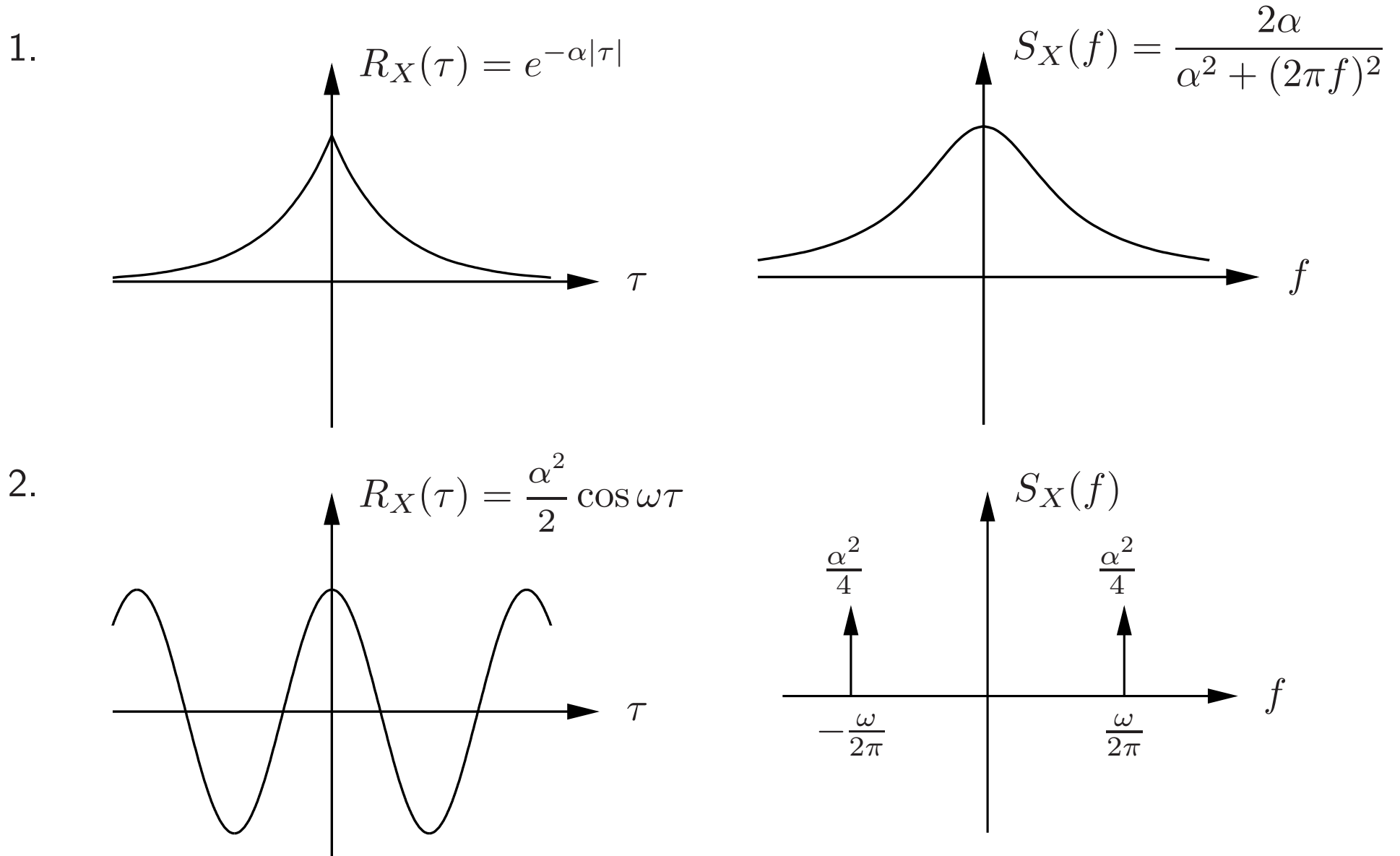
$$\int_{-f_2}^{-f_1} S_X(f) df + \int_{f_1}^{f_2} S_X(f) df = 2 \int_{f_1}^{f_2} S_X(f) df$$

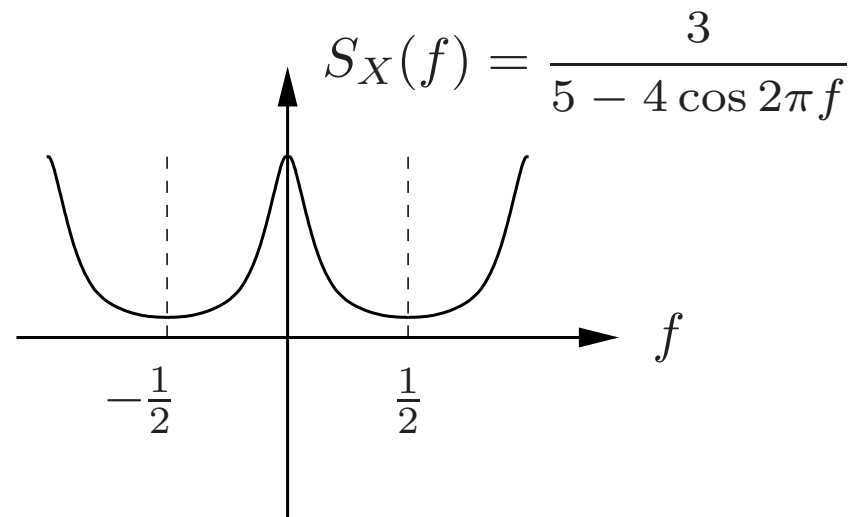
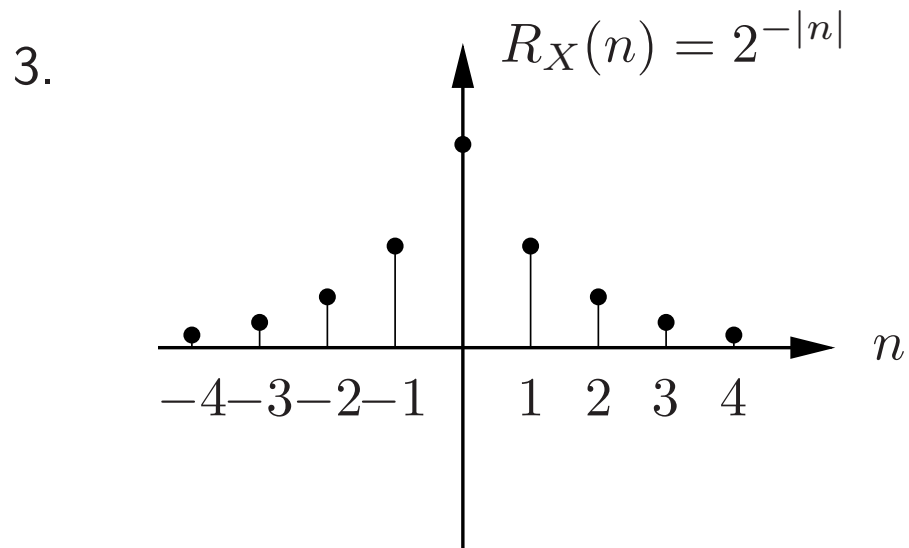
(we will show this soon)

- From property 3, it follows that  $S_X(f) \geq 0$ . Why?
- In general, a function  $S(f)$  is a psd if and only if it is real, even, nonnegative, and

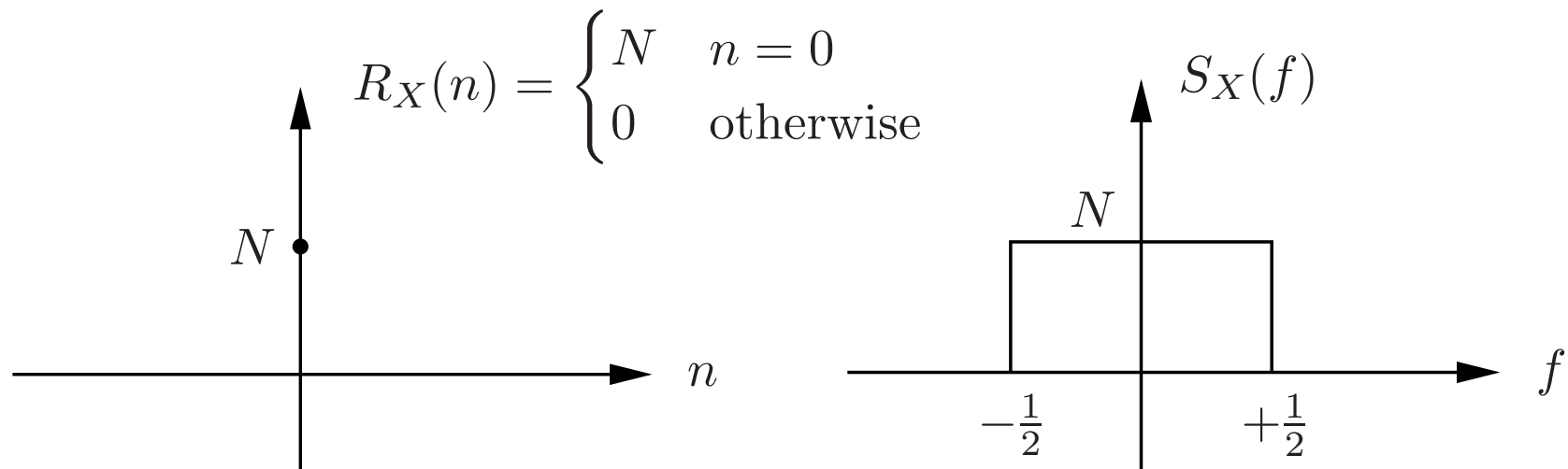
$$\int_{-\infty}^{\infty} S(f) df < \infty$$

# Examples





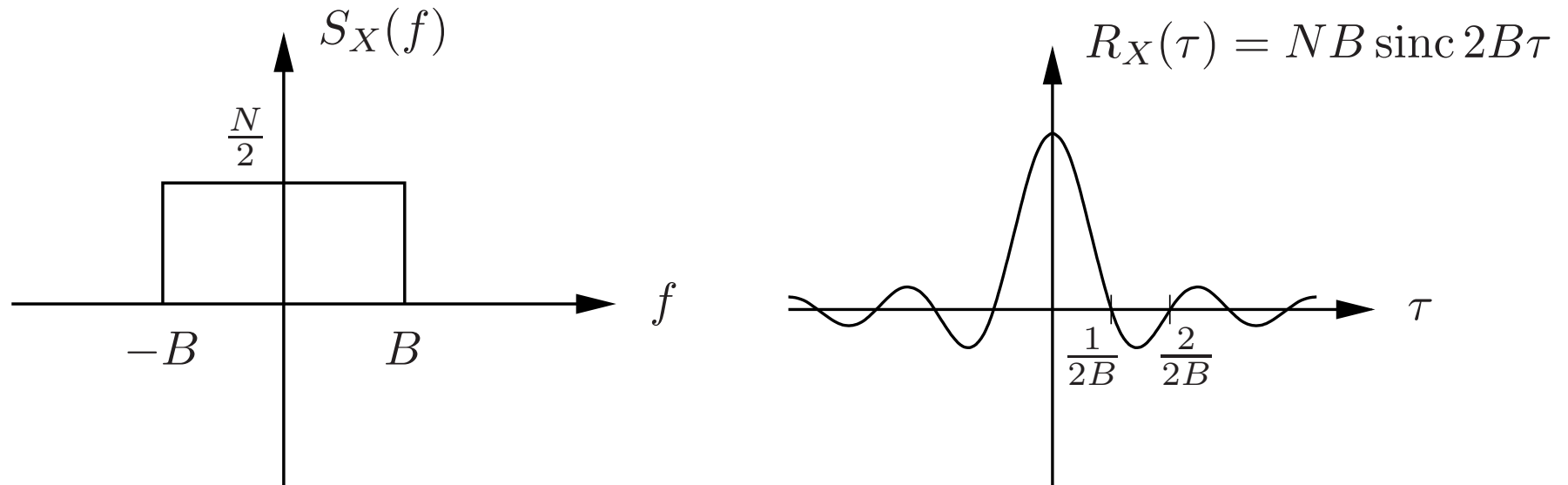
4. **Discrete time white noise process:**  $X_1, X_2, \dots, X_n, \dots$  zero mean, uncorrelated, with average power  $N$



If  $X_n$  is also a GRP, then we obtain a **discrete time WGN process**



5. **Bandlimited white noise process:** WSS zero mean process  $X(t)$  with



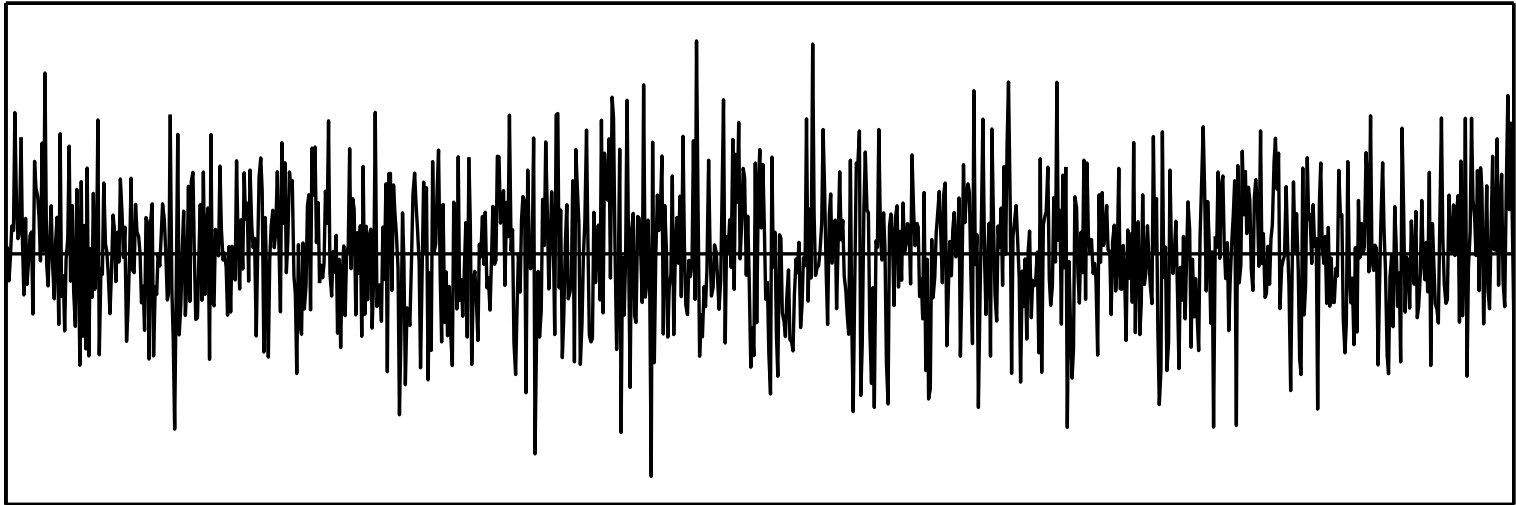
For any  $t$ , the samples  $X\left(t \pm \frac{n}{2B}\right)$  for  $n = 0, 1, 2, \dots$  are uncorrelated

6. **White noise process:** If we let  $B \rightarrow \infty$  in the previous example, we obtain a **white noise process**, which has

$$S_X(f) = \frac{N}{2} \quad \text{for all } f$$

$$R_X(\tau) = \frac{N}{2} \delta(\tau)$$

If, in addition,  $X(t)$  is a GRP, then we obtain the famous **white Gaussian noise (WGN) process**



- Remarks on white noise:
  - For a white noise process, all samples are uncorrelated
  - The process is not physically realizable, since it has infinite power
  - However, it plays a similar role in random processes to point mass in physics and delta function in linear systems
  - Thermal noise and shot noise are well modeled as white Gaussian noise, since they have very flat psd over very wide band (GHz)

# Stationary Ergodic Random processes

---

- Ergodicity refers to certain time averages of random processes converging to their respective statistical averages
- We focus only on mean ergodicity of WSS processes
- Let  $X_n$ ,  $n = 1, 2, \dots$ , be a discrete time WSS process with mean  $\mu$  and autocorrelation function  $R_X(n)$
- To estimate the mean of  $X_n$ , we form the sample mean

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

- The process  $X_n$  is said to be **mean ergodic** if:

$$\bar{X}_n \rightarrow \mu \quad \text{in mean square,}$$

$$\text{i.e., } \lim_{n \rightarrow \infty} \mathbb{E}[(\bar{X}_n - \mu)^2] = 0$$

- Since  $\mathbb{E}(\bar{X}_n) = \mu$ , this condition is equivalent to:

$$\text{Var}(\bar{X}_n) \rightarrow 0 \text{ as } n \rightarrow \infty$$

- We can express this condition in terms of  $C_X(n) = R_X(n) - \mu^2$  as follows

$$\begin{aligned} \text{Var}(\bar{X}_n) &= \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n \text{E}[(X_i - \mu)(X_j - \mu)] \\ &= \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n C_X(i - j) \\ &= \frac{1}{n} C_X(0) + \frac{2}{n^2} \sum_{i=1}^{n-1} (n - i) C_X(i) \end{aligned}$$

Since by definition,  $C_X(0) < \infty$ , the condition for mean ergodicity is:

$$\frac{2}{n^2} \sum_{i=1}^{n-1} (n - i) C_X(i) \rightarrow 0$$

- Example: Let  $X_n$  a WSS process with  $C_X(n) = 0$  for  $n \neq 0$ , then the process is mean ergodic
- The process does not need to have uncorrelated samples for it to be mean ergodic, however (see stationary Gauss-Markov process problem in HW7)

- Not every WSS process is mean ergodic

Example: Consider the coin with random bias  $P$  example in Lecture Notes 5.

The random process  $X_1, X_2, \dots$  is stationary

However, it is not mean ergodic, since  $\bar{X}_n \rightarrow P$  in m.s.

- Remarks:

- The process in the above example can be viewed as a **mixture** of IID Bernoulli( $p$ ) processes, each of which is stationary ergodic (it turns out that every SSS process is a mixture of stationary ergodic processes)
- Ergodicity can be defined for general (not necessarily stationary) processes (this is beyond the scope of this course)

# Mean Ergodicity for Continuous-time WSS Processes

---

- Let  $X(t)$  be WSS process with mean  $\mu$  and autocorrelation function  $R_X(\tau)$
- To estimate the mean, we form the **time average**

$$\bar{X}(t) = (1/t) \int_0^t X(\tau) d\tau$$

But what does this integral mean?

- **Integration of RP:** Let  $X(t)$  be a RP and  $h(t)$  be a function. Define the integral

$$\int_a^b h(t)X(t)dt$$

as the limit of a sum (as in Riemann integral of a deterministic function) in m.s.

Let  $\Delta > 0$  such that  $b - a = n\Delta$  and  $a \leq \tau_1 \leq a + \Delta \leq \tau_2 \leq a + 2\Delta \leq \dots \leq \tau_{n-1} \leq a + (n-1)\Delta \leq \tau_n \leq a + n\Delta = b$ , then the above integral exists if the Riemann sum

$$\sum_{i=1}^{n-1} h(\tau_i)X(\tau_i)\Delta \quad \text{has a limit in m.s.}$$

Moreover, if the random integral exists for all  $a, b$ , then we can define

$$\int_{-\infty}^{\infty} h(t)X(t)dt = \lim_{a,b \rightarrow \infty} \int_a^b h(t)X(t)dt \quad \text{in m.s.}$$

**Key fact:** The existence of the m.s. integral depends only on  $R_X$  and  $h$

More specifically, the above integral exists iff

$$\int_a^b \int_a^b R_X(t_1, t_2)h(t_1)h(t_2)dt_1dt_2$$

exists (in the normal sense)

- Now let's go back to mean ergodicity for continuous-time WSS process

By definition, mean ergodicity means that

$$\lim_{t \rightarrow \infty} \text{E}[(\bar{X}(t) - \mu_X)^2] \rightarrow 0$$

Since  $\text{E}(\bar{X}(t)) = \mu_X$ , the condition for mean ergodicity is the same as

$$\lim_{t \rightarrow \infty} \text{Var}(\bar{X}(t)) = 0$$

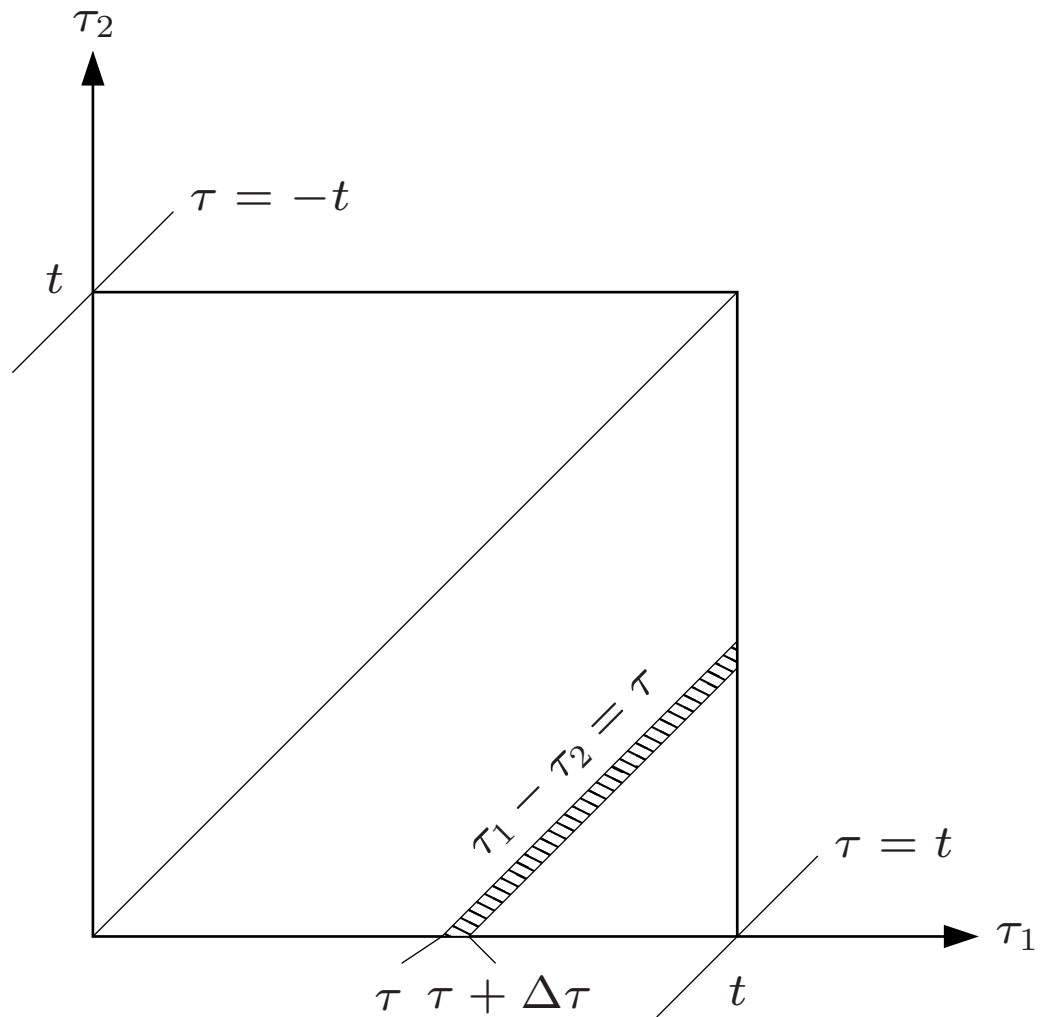
Now, consider

$$\begin{aligned}\mathbb{E}(\bar{X}^2(t)) &= \mathbb{E} \left[ \left( \frac{1}{t} \int_0^t X(\tau) d\tau \right)^2 \right] \\ &= \mathbb{E} \left( \frac{1}{t^2} \int_0^t \int_0^t X(\tau_1) X(\tau_2) d\tau_1 d\tau_2 \right) \\ &= \frac{1}{t^2} \int_0^t \int_0^t R_X(\tau_1, \tau_2) d\tau_1 d\tau_2 \\ &= \frac{1}{t^2} \int_0^t \int_0^t R_X(\tau_1 - \tau_2) d\tau_1 d\tau_2\end{aligned}$$

From the figure below, the double integral reduces to the single integral

$$\mathbb{E}(\bar{X}^2(t)) = \frac{2}{t^2} \int_0^t (t - \tau) R_X(\tau) d\tau$$





- Hence, a WSS process  $X(t)$  is mean ergodic iff

$$\lim_{t \rightarrow \infty} \frac{2}{t^2} \int_0^t (t - \tau) R_X(\tau) d\tau = \mu_X^2$$

- Example: Let  $X(t)$  be a WSS with zero mean and  $R_X(\tau) = e^{-|\tau|}$ . Evaluating the condition on mean ergodicity, we obtain

$$\frac{2}{t^2} \int_0^t (t - \tau) R_X(\tau) d\tau = \frac{2}{t^2} (e^{-t} + t - 1),$$

which  $\rightarrow 0$  as  $t \rightarrow \infty$ . Hence  $X(t)$  is mean ergodic